UHOH Rotational Raman Lidar (RRL)



Measured Parameters:

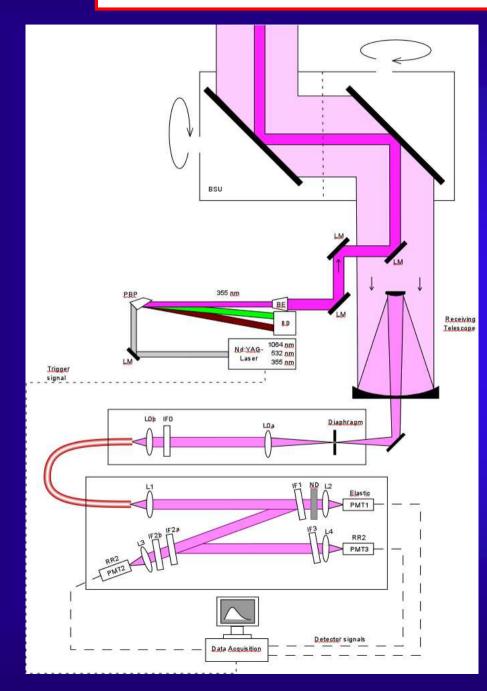
- Temperature
- optical aerosols properties
 (particle extinction coeff.,
 particle backscatter coeff.)
 with measurement uncertainties
 without a-priory assumptions
- cloud boundaries, BL height
- wind (via tracking of aerosols or clouds)







UHOH Rotations-Raman-Lidar: Set-up



Transmitter
355 nm
30 Hz, 300 mJ

Eye-safe at r > 300 m

Scanner

 ω_{max} = 10 °/s (azimuth) ω_{max} = 5 °/s (elevation)

Receiver

40 cm telescope 3 channels

 $\Delta r_{raw} = 3.75 \text{ m}; r_{max} = 15 \text{ km}$ (analog + pc)

 $\Delta r_{raw} = 36 \text{ m}; r_{max} = 72 \text{ km (pc)}$

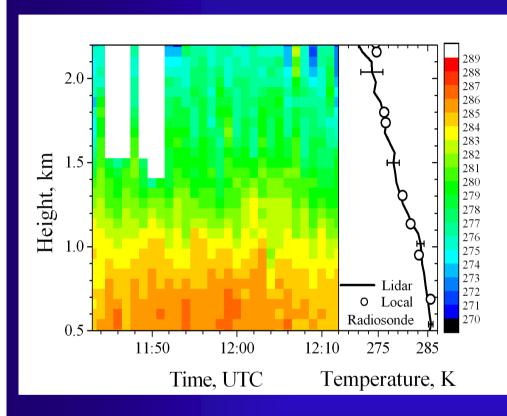
 $\Delta t_{raw} = 30 \text{ Hz}$

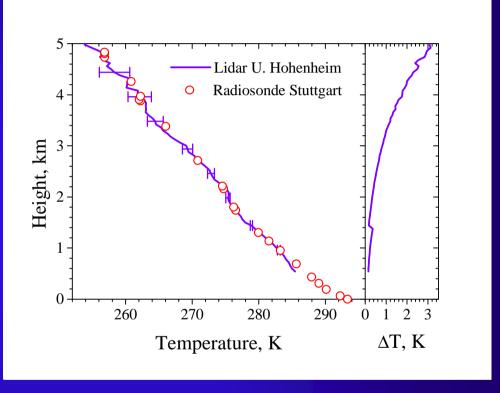




First test measurements were successful!

27 March 2006, vertical, near noon-time





 $\Delta t = 60 \text{ s}, \Delta z = 240 \text{ m}$

 $\Delta t = 20 \text{ minutes}, \Delta z = 120, 600 \text{ m}$

M. Radlach et al, ILRC 2006.



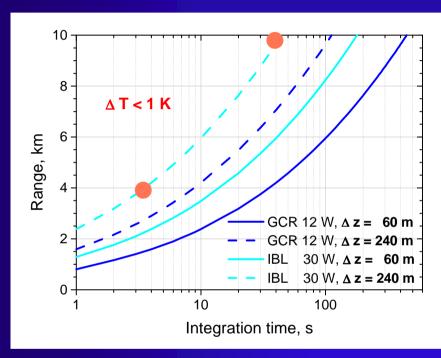


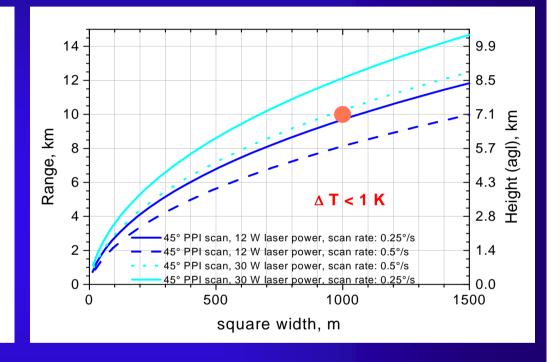
Expected Performance for COPS

(clear sky, no background)

Profiling

PPI scan





 $\Delta T < 1$ K, $\Delta z = 0.25$ km, $\rightarrow \Delta t$ of a few s in the BL + lower trop $\rightarrow \Delta t = 30$ s for $r_{max} = 10$ km ΔT < 1 K, 1 km square width $\rightarrow \Delta t$ = 6 minutes for r_{max} = 10 km

First field deployment in July at Hornisgrinde within PRINCE.



